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(57) Abstract :

The Exploring the world can be dangerous and rough such as in was fields and rug grater rain roads, which are hard to access with normal vehicles. The objective of this work was to create electronic spider that has the ability to navigate terrain that is impassable for most other land vehicles. In this design, the spider legs have the freedom of movement as those of biological spider. The electronic spider is a device used in monitoring surroundings wirelessly. The spider robot function without interfacing, it can easily adapt to the new situation or obstacles due to its legs of locomotion on like the ordinary two legs robot. The user of this spider robotic system poses prefecture solution to such problems, eradicating the deem and for human kind to access such places and regularly providing information on the state of such environment that would not otherwise be available for humanity

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